

parametric, reusable, portable

programming abstraction

modelling known, common, efficient

parallelism exploitation pattern

PARAMS → to distinguish different versions or usages → FUNCT  
→ NON FUNCT

REUSABLE → !

VECTOR PROCESSORS  
GPUS

PORTABLE → across hw/sw archie  
very different hw COW/NOW  
GRIDS

KNOWN, COMMON

EFFICIENT

## SKELTON ADVANTAGE

programmability (separation of concerns)

fast prototyping

- debugging (fine tuning)

Correctness (Termination)

- optimisations

↳ compositionality

- performance models

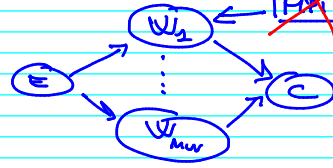
portability - FUNCTIONAL

- NON FUNCT. (PERFORMANCE)

## WEAKNESS

lack of "configurability"  
expandability  
of the orbital set

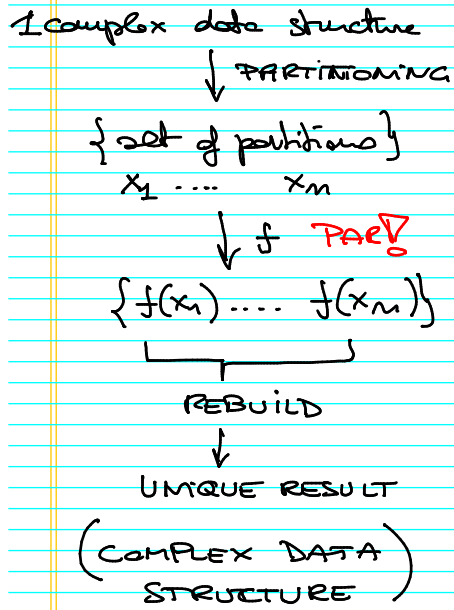
low form  $\equiv SK_i$



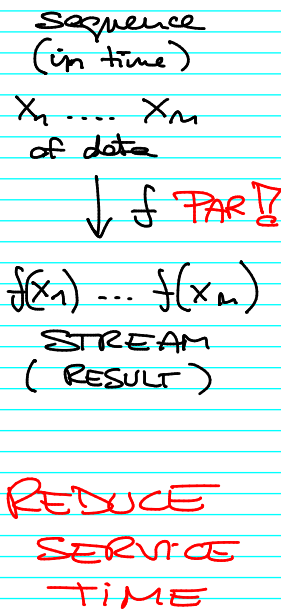
$$SK = \{ SK_1 \dots SK_m \}$$

↑            ↑  
?            ?

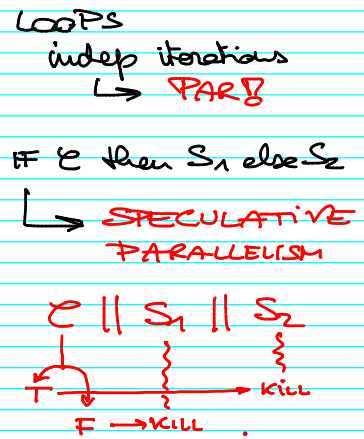
### DATA PARALLEL PATTERNS



### STREAM PAR. PATTERNS

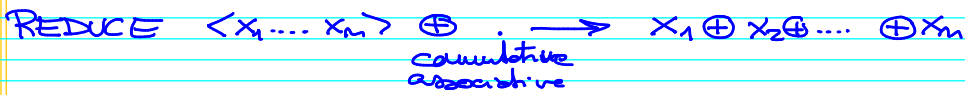
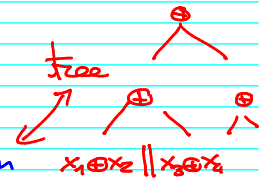
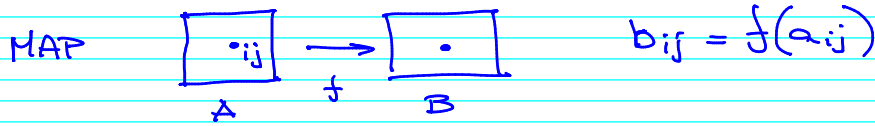


### CONTROL PAR PATTERNS



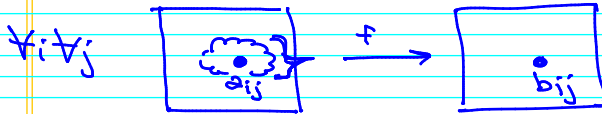
REDUCE LATENCY

# DATA PARALLEL PATTERNS

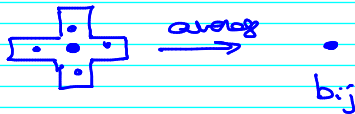


DIVIDE & CONQUER divide phase ( $\rightarrow$  {subproblems})  
 conquer phase (sums up solutions)

## STENCIL



$f: \text{average}(a_{ij}, a_{i-1,j}, a_{i+1,j}, a_{i,j-1}, a_{i,j+1}) \rightarrow b_{ij}$



dimension of the stencil may be dynamic

SCAN  $\langle x_1 \dots x_m \rangle \oplus$



$\langle x_1, x_1 \oplus x_2, x_1 \oplus x_2 \oplus x_3, \dots, x_1 \oplus x_2 \oplus \dots \oplus x_m \rangle$